

# How to control the XTA from a python script

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version	1.0.1
scope	Example. This code is provided as example code for a user to base their code on.
description	How to control the XTA from a python script
boards	Unless otherwise specified, this example runs on the SliceKIT Core Board, but can easily be run on any XMOS device by using a different XN file.

There are occasions when the inbuilt XTA command scripting mechanism does not offer the required level of power and/or flexibility. For example, you may wish to pass arguments to a script, use the return value of one command as input to another or make use of conditional/looping constructs. With this in mind, the XTA provides an interface which allows the tool to be controlled from Python scripts.

For example, compile the following code:

```
#include <stdlib.h>
#include <xs1.h>

port p1 = XS1_PORT_1A;
port p2 = XS1_PORT_1B;

int main() {
    int x;

    #pragma xta endpoint "input"
    p1 :> x;

    // Checks for errors..
    if (x == 1) {
        #pragma xta label "error_case"
        exit(1);
    }

    // do some computation here..

    #pragma xta endpoint "output"
    p2 <: 0;
    return 0;
}
```

As an example, assume that you want to time from the input to the output, set a requirement and exclusion, and this this must be done from a Python script. To achieve this, place the following lines in a file, e.g. script.py:

```
import java

try:
    xta.load("a.xe") ;

except java.lang.Exception, e:
    print e.getMessage()

try:
    xta.addExclusion("error_case")
    ids = xta.analyzeEndpoints("input", "output")
    for id in ids:
        print xta.getRouteDescription(id) + ":",
        print xta.getWorstCase(id, "ns"),

except java.lang.Exception, e:
    print e.getMessage()
```

The above script can then be run using the XTA *source* command:

```
xta source script.py -exit
```

Note: See the Xmos-Timing-Analyzer-Manual for further information on available interface methods.



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